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L1	99	laser and ((noise or speckle$1 or artifact$1) near3 (reduct$3 or remov$3)) and (gaussian near3 filter$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/08 12:49
L2	4	(("5589942") or ("5621529")).PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/08 12:49

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1 Model-based object recognition in dense-range images—a review

Farshid Arman, J. K. Aggarwal
March 1993 **ACM Computing Surveys (CSUR)**, Volume 25 Issue 1

Full text available: pdf(3.42 MB) Additional Information: full citation, abstract, references, citings, index terms, review

The goal in computer vision systems is to analyze data collected from the environment and derive an interpretation to complete a specified task. Vision system tasks may be divided into data acquisition, low-level processing, representation, model construction, and matching subtasks. This paper presents a comprehensive survey of model-based vision systems using dense-range images. A comprehensive survey of the recent publications in each subtask pertaining to dense-range image object recogni ...

Keywords: 3D object recognition, 3D representations, CAD-based vision, dense-range images, image understanding

2 Anisotropic geometric diffusion in surface processing

U. Clarenz, U. Diewald, M. Rumpf
October 2000 **Proceedings of the conference on Visualization '00**

Full text available: pdf(4.65 MB) Additional Information: full citation, index terms

Keywords: geometric modeling, image processing, numerical analysis

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